



YASKAWA

YASKAWA AC Drive-V1000 Option CC-Link Installation Manual

Type SI-C3/V

To properly use the product, read this manual thoroughly and retain for easy reference, inspection, and maintenance. Ensure the end user receives this manual.

V1000オプションユニット CC-Link通信 取扱説明書

形式 SI-C3/V

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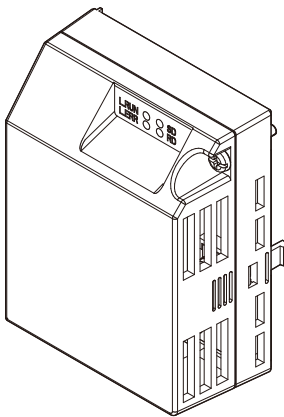




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1 Preface and Safety

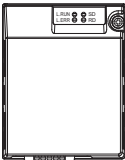
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1 Preface and Safety


◆ Applicable Documentation

The following manuals are available for the CC-Link Option:

Option Unit

	V1000 Option CC-Link Installation Manual (this book) Manual No. : TOBPC73060022
	Read this manual first. The installation manual is packaged with the CC-Link Option and contains a basic overview of wiring, settings, functions, and fault diagnoses.
	V1000 Option CC-Link Technical Manual Manual No. : SIEPC73060022
	The technical manual contains detailed information and command registers. To obtain the technical manual access the site below: http://www.e-mechatronics.com

Yaskawa Drive

	V1000 Series AC Drive Technical Manual
	This manual describes installation, wiring, operation procedures, functions, troubleshooting, maintenance, and inspections to perform before operation. To obtain instruction manuals for Yaskawa products access the site below: http://www.e-mechatronics.com
	V1000 Series AC Drive Quick Start Guide
	This guide is packaged together with the product. It contains basic information required to install and wire the drive. This guide provides basic programming and simple set-up and adjustment.

◆ Terms

Note: Indicates supplementary information that Yaskawa highly recommends be followed, even though equipment may not be at risk.

Drive: Yaskawa AC Drive-V1000 Series

CC-Link Option: Yaskawa AC Drive-V1000 Option CC-Link

≥ **1011:** Indicates a drive feature or function that is only available in drive software version 1011 or later.

◆ Registered Trademarks

- CC-Link is a registered trademark of the CC-Link Partner Association.
- Other company names and product names listed in this manual are registered trademarks of those companies.

◆ Supplemental Safety Information

Read and understand this manual before installing, operating, or servicing this option unit. The option unit must be installed according to this manual and local codes.

The following conventions are used to indicate safety messages in this manual. Failure to heed these messages could result in serious or possibly even fatal injury or damage to the products or to related equipment and systems.

DANGER

Indicates a hazardous situation, which, if not avoided, will result in death or serious injury.

WARNING

Indicates a hazardous situation, which, if not avoided, could result in death or serious injury.

CAUTION

Indicates a hazardous situation, which, if not avoided, could result in minor or moderate injury.

NOTICE

Indicates an equipment damage message.

1 Preface and Safety

■ General Safety

General Precautions

- The diagrams in this section may include option units and drives without covers or safety shields to illustrate details. Be sure to reinstall covers or shields before operating any devices. The option should be used according to the instructions described in this manual.
- Any illustrations, photographs, or examples used in this manual are provided as examples only and may not apply to all products to which this manual is applicable.
- The products and specifications described in this manual or the content and presentation of the manual may be changed without notice to improve the product and/or the manual.
- When ordering a new copy of the manual due to damage or loss, contact your Yaskawa representative or the nearest Yaskawa sales office and provide the manual number shown on the front cover.

DANGER

Heed the safety messages in this manual.

Failure to comply will result in death or serious injury.

The operating company is responsible for any injuries or equipment damage resulting from failure to heed the warnings in this manual.

NOTICE

Do not expose the drive to halogen group disinfectants.

Failure to comply may cause damage to the electrical components in the option unit.

Do not pack the drive in wooden materials that have been fumigated or sterilized.

Do not sterilize the entire package after the product is packed.

Do not modify the drive circuitry.

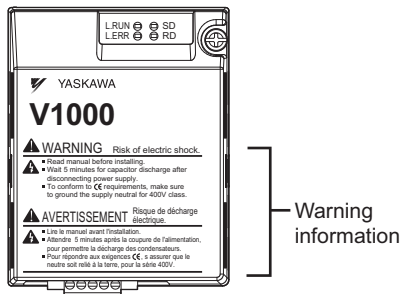
Failure to comply could result in damage to the drive and will void warranty.

YASKAWA is not responsible for any modification of the product made by the user. This product must not be modified.

■ Option Unit Label Warnings

Warning information is displayed on the option unit as shown in the figure below. Follow all warnings and safety instructions when using the product.

When using the drive in an area that may require displaying warning information in Japanese or Chinese, a warning label sticker is provided with the CC-Link Option. This sticker can be placed over the English and French warnings on the front of the CC-Link Option.



■ Warning Contents

⚠ WARNING Risk of electric shock.

- ⚡**
 - Read manual before installing.
 - Wait 5 minutes for capacitor discharge after disconnecting power supply.
 - To conform to **CE** requirements, make sure to ground the supply neutral for 400V class.

⚠ AVERTISSEMENT Risque de décharge électrique.

- ⚡**
 - Lire le manuel avant l'installation.
 - Attendre 5 minutes après la coupure de l'alimentation, pour permettre la décharge des condensateurs.
 - Pour répondre aux exigences **CE**, s'assurer que le neutre soit relié à la terre, pour la série 400V.

2 Product Overview

◆ About This Product

CC-Link Option (Model: SI-C3/V) is designed for connecting a drive to a field network using the CC-Link protocol. This option unit is conforming to CC-Link Ver.1.10.

By installing the CC-Link Option to a drive, it is possible to do the following from a CC-Link master device:

- operate the drive
- monitor the operation status of the drive
- change parameter settings.



Figure 1 CC-Link Approved

◆ Applicable Model

The CC-Link Option can be used with the drive models in [Table 1](#).

Table 1 Applicable Model

Drive	Software Version <I>
CIMR-V□□A□□□□AA□	≥ 1011
CIMR-V□□A□□□□BA□	≥ 1011
CIMR-V□□A□□□□FA□	≥ 1011

<I> See “PRG” on the drive nameplate for the software version number.

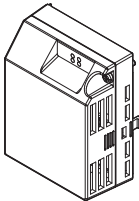
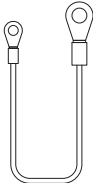

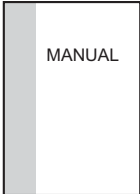
3 Receiving

Please perform the following tasks after receiving the CC-Link Option:

- Inspect the CC-Link Option for damage.
If the CC-Link Option appears damaged upon receipt, contact the shipper immediately.
- Verify receipt of the correct model by checking the information on the nameplate (see [Figure 2](#)).
- If you have received the wrong model or the CC-Link Option does not function properly, contact your supplier.

◆ Contents and Packaging

Table 2 Contents of Package

Description:	Option Unit	Ground Cables	Warning Label Stickers	Installation Manual
-				
Quantity:	1	4	1	1

◆ Tool Requirements

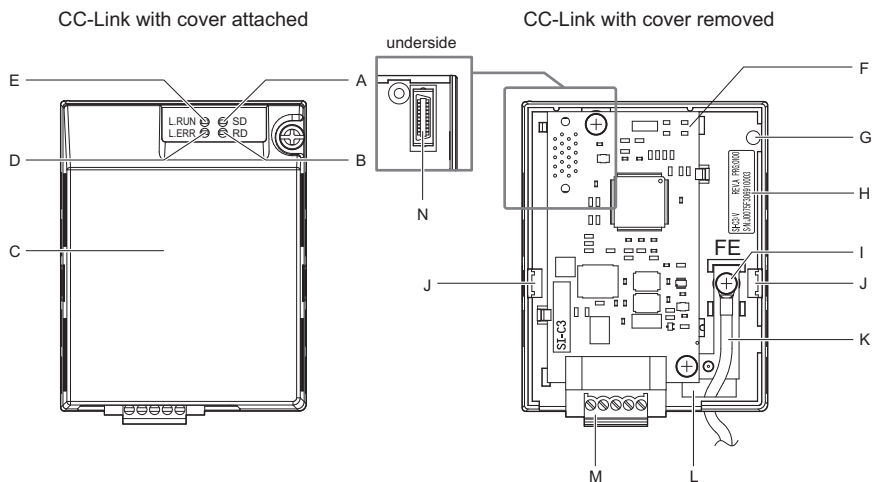
A Phillips screwdriver (M3, M3.5 to M6 <1> metric or (#1, #2 <1>) U.S. standard size is required to install the CC-Link Option.

<1> Screw sizes vary by drive capacity. Select a screwdriver that matches the drive capacity.

Note: Tools required to prepare CC-Link cables for wiring are not listed in this manual.

4 CC-Link Option Components

◆ CC-Link Option



- | | |
|--|--|
| A – LED (SD) | H – Nameplate |
| B – LED (RD) | I – Function Earth cable connection (FE) |
| C – Option cover | J – Mounting clip |
| D – LED (L.ERR) | K – Ground Cable <1> |
| E – LED (L.RUN) | L – Through-hole for cable |
| F – CC-Link PCB | M – Terminal block |
| G – Attachment screw hole for option cover | N – Option connector |

<1> Cables are not connected to the CC-Link Option and are packaged separately in the box.

Figure 2 Option Unit

Note: For details on the LEDs, *Refer to CC-Link Option LED Display on page 14* and *Fault LED Display on CC-Link Option Side on page 35*.

◆ Dimensions

The installed CC-Link Option adds 27 mm to the total depth of the drive.

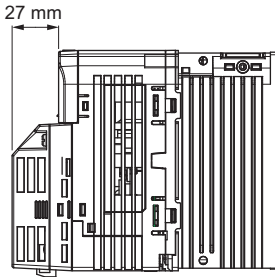


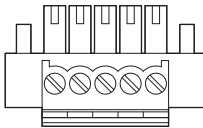
Figure 3 Dimensions

◆ Terminal Block

Table 3 Terminal Descriptions

Terminal	Name	Description
1	DA	Comm. Data +
2	DB	Comm. Data -
3	DG	Signal Ground
4	SLD	Shield
5	SLD	Shield

Top View
(looking from the very top of the CC-Link Option)



Bottom View

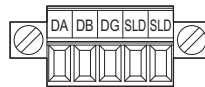


Figure 4 CC-Link Option Terminal Block

4 CC-Link Option Components

◆ CC-Link Option LED Display

Table 4 CC-Link Operation LED Status

Name	Indication		Operating Status	Remarks
	Color	Status		
L.RUN	Green	ON	Normal operation	<ul style="list-style-type: none"> Receiving data normally
		OFF	Timed out	<ul style="list-style-type: none"> Timed out waiting to receive Logging onto the network During reset
L.ERR	Red	ON	CRC error	<ul style="list-style-type: none"> CRC error Station address setting error (F6-10 = 0)
		OFF	During communications	<ul style="list-style-type: none"> Normal communications During reset
SD	Red	ON	Sending data	<ul style="list-style-type: none"> Sending data Note: LED may appear to flash with slower baud rates.
		OFF	No data transfer	<ul style="list-style-type: none"> No data being sent During reset
RD	Red	ON	Detecting data received	<ul style="list-style-type: none"> Detecting data that was received Note: LED may appear to flash with slower baud rates.
		OFF	Waiting for data	<ul style="list-style-type: none"> Data not yet received During reset

◆ Setting Station Address

Set drive parameter F6-10 to a station address (Range 1 to 64) unique to the network. If set to 0, the L.ERR light will turn on and a Station Address Error (AEr) will occur.

5 Installation Procedure

◆ Section Safety

DANGER

Electrical Shock Hazard

Do not connect or disconnect wiring while the power is on.

Failure to comply will result in death or serious injury.

Disconnect all power to the drive, wait at least five minutes after all indicators are off, measure the DC bus voltage to confirm safe level, and check for unsafe voltages before servicing to prevent electric shock. The internal capacitor remains charged even after the power supply is turned off. The charge indicator LED will extinguish when the DC bus voltage is below 50 Vdc.

WARNING

Electrical Shock Hazard

Do not remove option cover while the power is on.

Failure to comply could result in death or serious injury.

The diagrams in this section may include option units and drives without covers or safety shields to show details. Be sure to reinstall covers or shields before operating any devices. The option should be used according to the instructions described in this manual.

Do not allow unqualified personnel to use equipment.

Failure to comply could result in death or serious injury.

Maintenance, inspection, and replacement of parts must be performed only by authorized personnel familiar with installation, adjustment, and maintenance of this product.

Do not remove option cover while the power to the drive is on.

Failure to comply could result in death or serious injury.

Do not use damaged wires, place excessive stress on wiring, or damage the wire insulation.

Failure to comply could result in death or serious injury.

WARNING

Fire Hazard

Tighten all terminal screws to the specified tightening torque.

Loose electrical connections could result in death or serious injury by fire due to overheating of electrical connections.

NOTICE

Damage to Equipment

Observe proper electrostatic discharge procedures (ESD) when handling the option unit, drive, and circuit boards.

Failure to comply may result in ESD damage to circuitry.

Never shut the power off when the drive is outputting voltage.

Failure to comply may cause the application to operate incorrectly or damage the drive.

Do not operate damaged equipment.

Failure to comply may cause further damage to the equipment.

Do not connect or operate any equipment with visible damage or missing parts.

Do not use unshielded cable for control wiring.

Failure to comply may cause electrical interference resulting in poor system performance.

Use shielded twisted-pair wires and ground the shield to the ground terminal of the drive.

Properly connect all pins and connectors.

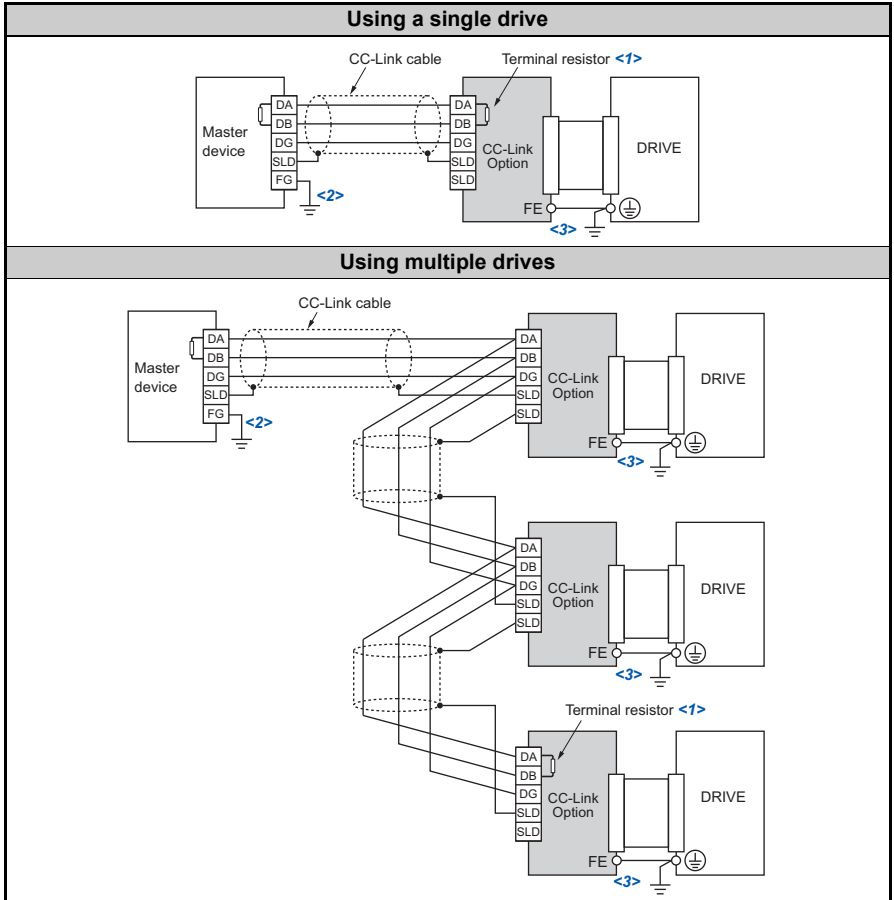
Failure to comply may prevent proper operation and possibly damage equipment.

Check wiring to ensure that all connections are correct after installing the option unit and connecting any other devices.

Failure to comply may result in damage to the option unit.

◆ Wiring Diagram

Table 5 Wiring Diagram



<1> The user must set up the drive for terminal resistor. For instructions, see [Terminal Resistor Connection on page 22](#).

<2> Make sure that the FG terminal on the master drive is grounded properly.

<3> The FE terminal on the CC-Link Option is supplied with a ground cable that should be connected to the ground terminal on the drive.

5 Installation Procedure

◆ Installing the Option Unit

Remove the front cover of the drive before installing the CC-Link Option. Follow the directions below for proper installation.

1. Switch off the power supply to the drive.

DANGER! Electrical Shock Hazard - Do not connect or disconnect wiring while the power is on. Failure to comply will result in death or serious injury. Before installing the CC-Link Option, disconnect all power to the drive. The internal capacitor remains charged even after the power supply is turned off. The charge indicator LED will extinguish when the DC bus voltage is below 50 Vdc. To prevent electric shock, wait at least five minutes after all indicators are off and measure the DC bus voltage level to confirm safe level.

2. Remove the front cover. The original drive front cover may be discarded because it will be replaced by the CC-Link Option cover in step 8.

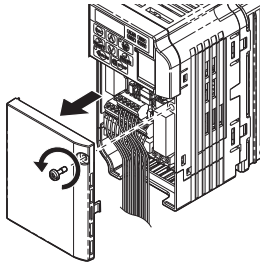


Figure 5 Remove Front Cover

3. Remove the bottom cover and connect the CC-Link Option ground cable to the ground terminal.

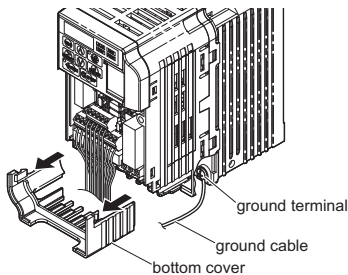
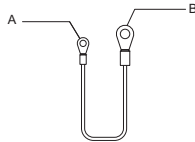


Figure 6 Connect Ground Cable

Note: The four different ground cables packaged with the CC-Link Option connect the unit to different models. Select the proper ground cable from the CC-Link Option kit depending on drive size.



A – Option unit connection: screw size = M3

B – Drive-side connection: screw size = M3.5 to M6

Figure 7 Ground Cable

Note: Cover removal for certain larger models with a Terminal Cover:

-Single-Phase 200 V Class: CIMR-V□BA0006 to BA0018

-Three-Phase 200 V Class: CIMR-V□2A0008 to 2A0069

-Three-Phase 400 V Class: All models

Remove the terminal cover before removing the bottom cover to install the CC-Link Option.
Replace the terminal cover after wiring the CC-Link Option.

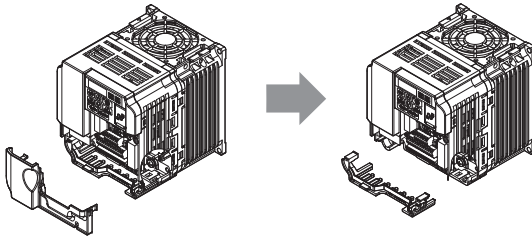


Figure 8 Models with Terminal Cover

4. Reattach the bottom cover.
5. Connect the CC-Link Option to the drive. Properly secure the tabs on the left and right sides of the CC-Link Option to the drive case.

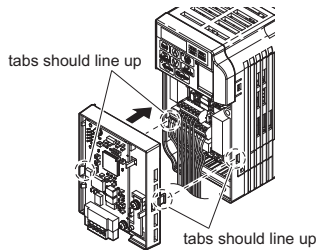


Figure 9 Attach CC-Link Option

5 Installation Procedure

6. Connect the ground cable from the drive ground terminal to the CC-Link Option ground. When wiring the CC-Link Option, pass the ground cable through the inside of the drive bottom cover, then pass the ground cable into the through-hole at the front of the CC-Link Option.

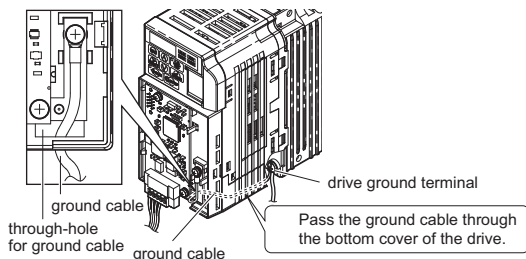


Figure 10 Ground Cable Connection

7. Connect the communications cable to the terminal block. Refer to Procedure on page 21.
8. Attach the CC-Link Option cover to the front of the CC-Link Option.

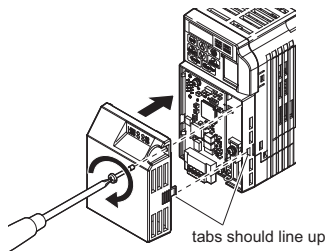


Figure 11 Attach Cover

Note: When using the drive in an area that may require displaying warning information in Japanese or Chinese, a sticker has been provided with the CC-Link Option. This sticker can be placed over the English and French warnings on the front of the CC-Link Option.

◆ Communication Cable Wiring

■ Procedure

Follow the instructions below to connect the communications cable to the terminal block.

NOTICE: Tighten all terminal screws according to the specified tightening torque. Tightening screws too tight could damage the terminal block, and leaving screws too tight loose can cause a short-circuit or drive malfunction.

1. Connect the communications cable to the terminal block as shown in the diagram below.

Note: Communication lines should be separated from main circuit wiring and other electrical lines.
(Tightening torque: 0.22 to 0.25 (N·m))

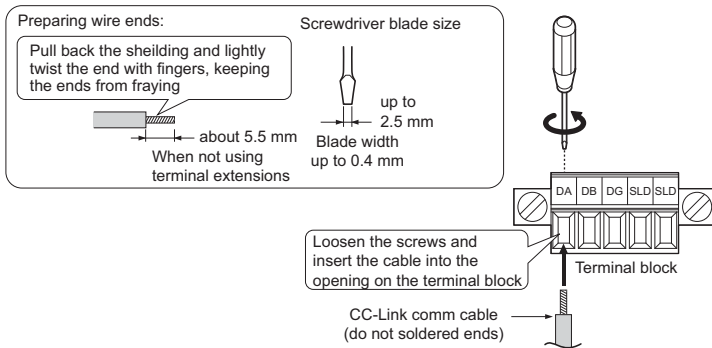


Figure 12 Comm Cable Wiring

2. Ensure all wiring connections are tightened and wire insulation is not pinched in the terminal block. Remove any stray wire strands that touch other terminals.

5 Installation Procedure

3. After the terminal block is fully attached to the option unit, tighten the screws on the left and right sides of the terminal block. (Tightening torque: 0.22 to 0.25 (N·m))

Note: Be sure to put the option cover back on after you have completed all necessary wiring.

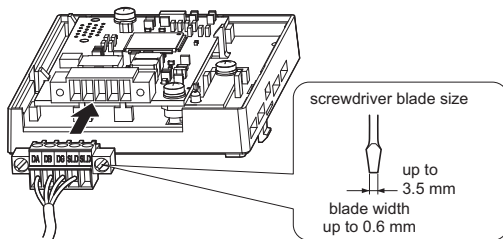


Figure 13 Terminal Block Installation

■ Communication Cable Specifications

Use only CC-Link dedicated cable. Warranty does not cover other cable types. For information of cables, refer to the CC-Link website at <http://www.cc-link.org/>.

■ Terminal Resistor Connection

When the CC-Link Option is the last station connected in a CC-Link network, the terminal resistor needs to be set to that CC-Link Option. Follow the instructions below.

1. Cut the terminal resistor tube as shown.

Note: For the terminal resistor, either use what is already built into the master unit, or use a standard-market resistor of $110\ \Omega$, $\pm 5\%$ (1/2 W).

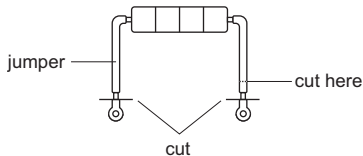


Figure 14 Terminal Resistor

2. Loosen the attachment screw and insert the terminal resistor described in the first step between terminals DA and DB.

Note: Make sure that the option cover is put back on after wiring is complete.

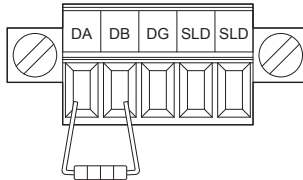


Figure 15 Terminal Resistor Wiring

6 CC-Link Option Drive Parameters

Confirm proper setting of the all parameters in *Table 6* before starting network communications.

Table 6 Parameter Settings

No.	Name	Description	Default
b1-01	Frequency Reference Selection </>	Selects the frequency reference input source. 0: Operator - Digital preset speed d1-01 to d1-17 1: Terminals - Analog input terminal A1 or A2 2: MEMOBUS communications 3: Option PCB 4: Pulse Input (Terminal RP)	1
b1-02	Run Command Selection </>	Selects the run command input source. 0: Operator - RUN and STOP keys 1: Digital input terminals S1 to S7 2: MEMOBUS communications 3: Option PCB	1
F6-01	Operation Selection after Communications Error	Determines drive response when a bUS error is detected during communications with the CC-Link Option. 0: Ramp to Stop 1: Coast to Stop 2: Fast-Stop 3: Alarm Only </>	1
F6-02	External Fault Detection Conditions (EF0)	Sets the conditions for detecting an external fault (EF0). 0: Always detected. 1: Detected only during operation.	0
F6-03	Stopping Method for External Fault from Communication Option	Determines drive response for external fault input (EF0) detection during CC-Link communication. 0: Ramp to Stop 1: Coast to Stop 2: Fast-Stop 3: Alarm Only </>	1
F6-04	bUS Error Detection Delay Time	Set the maximum time the drive should wait for a communication error to occur (bUS). 0.0 to 5.0 s	0.0 s </>
F6-07 </>	NetRef/ComRef Selection Function	0: Multi-step speed reference disabled (F7 mode) 1: Multi-step speed reference allowed (V7 mode)	1

6 CC-Link Option Drive Parameters

No.	Name	Description	Default
F6-08 <>	Reset Communication Related Parameters	Determines which communication-related parameters are set back to their original default values when the drive is initialized. 0: Do not reset F6-□□ and F7-□□ parameters when the drive is initialized using parameter A1-03. 1: Rest F6-□□ and F7-□□ parameters when the drive is initialized using parameter A1-03. Note: Setting this parameter does not affect communication-related parameters.	0
F6-10 <>	Station Address <6>	0 to 64	0
F6-11 <>	Comm Speed	0: 156 kbps 1: 625 kbps 2: 2.5 Mbps 3: 5 Mbps 4: 10 Mbps	0

- <1> To start and stop the drive with the CC-Link master device using serial communications, set b1-02 to “3”. To control the frequency reference of the drive via the master device, set b1-01 to “3”.
- <2> If set to 3, then the drive will continue to operate when a fault is detected. Take proper measures such as installing an emergency stop switch.
- <3> The drive default setting is 2.0 s, but this default setting will automatically be changed to 0.0 s when SI-C3/V is connected.
- <4> Software versions 1012 and later have F6-07 and F6-08 both set to 1.
- <5> Power must be cycled in order for any setting changes to take affect.
- <6> All station addresses must be unique. If set to 0, the L.ERR light will turn on and a Station Address Error (AEr) will occur.

7 Basic Functions

This interface allows the drive to be connected to a CC-Link network as a remote device, making it possible to operate, adjust settings, and monitor the operation status of the drive using the PLC program. Both bit and word data cyclic transmission are available, and high speed communication up to 10 Mbps is possible.

Below is a description of the basic CC-Link functions that can be performed by the PLC.

Note: Set parameters when operating the drive from a PLC. For instructions, see [Refer to CC-Link Option Drive Parameters on page 24](#).

◆ Monitors

The user can monitor drive operating status from a PLC.

To do so, the monitor should be set up as follows:

1. Sets the monitor code to the remote register RW_{W0} .
2. Switch the RYC signal on.
 - Data for the monitor code is stored in the PLC's buffer memory.

Note: Refer to the V1000 Option CC-Link Technical Manual for information on the monitor codes and units.

◆ Reading and Setting Parameters

The PLC can write drive parameters, read drive data and operation status, and change settings.

Follow the directions below.

1. Set the command code to remote register RW_{W2} .
 - Set the write data to RW_{W3} as needed.
2. Switch on the RYF signal (request to execute the command code).
 - Drive executes the process and reply data that correspond with the command code.
 - Command codes for drive parameters should be calculated by adding the values shown below to the MEMOBUS register number.

Read command code: MEMOBUS register + 1000H

Write command code: MEMOBUS register + 2000H

EXAMPLE: Acceleration time command code for C1-01 is 200H. Get the read command code by adding 1000H, yielding 1200H

- Note:**
1. Refer to the V1000 Option CC-Link Technical Manual for information on the command codes and write data.
 2. Refer to the MEMOBUS/Modbus Data Table in Appendix C of the V1000 Technical Manual for a list of monitor data using the MEMOBUS/Modbus message area.

8 CC-Link Data Table

◆ Remote I/O

The drive takes up a single station address in the buffer memory or the PLC. The table below shows the drive I/O as seen from the PLC side.

Note: Refer to the PLC's programming manual for information on the PLC's buffer memory.

■ PLC → Drive

Table 7 Remote I/O Table (PLC → Drive)

Signal	Name	Description	Default
RY0	Forward Run	ON: Forward Run Command, OFF: Stop	–
RY1	Reverse Run	ON: Reverse Run Command, OFF: Stop	–
RY2	Terminal S3 Function	Multi-function input: H1-03	(H1-03 = 24: External Fault)
RY3	Terminal S4 Function	Multi-function input: H1-04	(H1-04 = 14: Fault Reset)
RY4	Terminal S5 Function	Multi-function input: H1-05	(H1-05 = 3: Multi-Step Speed 1)
RY5	Terminal S6 Function	Multi-function input: H1-06	(H1-06 = 4: Multi-Step Speed 2)
RY6	Terminal S7 Function	Multi-function input: H1-07	(H1-07 = 6: Jog Reference)
RY7, 8	Reserved	–	–
RY9	Drive Output Interrupt	ON: Motor coasts to stop. OFF: Drive will begin operating as soon as a Run command is given.	–
RYA	External Fault	ON: External Fault Input (EF0)	–
RYB	Motor Revolutions / Output Frequency Switch	Data contents for the remote register RW_{R1} switches between motor revolutions and output frequency.	Motor rotations are displayed only when H6-01 = 3 and A1-02 = 0.
RYC	Monitor Reference	ON: Monitor data specified in the monitor code is set to remote register RW_{R0} .	–
RYD	Frequency Setting 1	Frequency set to remote register RW_{W1} becomes the operating frequency for the drive.	–

Signal	Name	Description	Default
RYE	Frequency Reference 2	Sets the frequency in the remote register RW_{W1} to parameter d1-01 (Frequency Reference 1) and as the drive's main frequency reference at the same time. Note: If the frequency reference is set to be provided by the LED operator (i.e, b1-01 = 0), then switching on RYE changes the frequency reference.	All parameter settings are saved when this flag is switched on. Triggered by the rising edge of the signal.
RYF	Command Code Execute Request	Request to execute the command code.	Triggered by the rising edge of the signal.
RY10 to 13	Reserved	-	-
RY14	Terminal S1 Function	Multi-function input: H1-01	Function is disabled when for the Forward Run Command (H1-01 = 40).
RY15	Terminal S2 Function	Multi-function input: H1-02	Function is disabled when for the Reverse Run Command (H1-02 = 41).
RY16 to 19	Reserved	-	-
RY1A	Fault Reset	Resets a drive fault	-
RY1B to 1F	Reserved	-	-

- Note:**
1. If making frequent setting changes, use RYD (Frequency Reference 1 flag) for setting the register. Using RYE (Frequency Reference 2 flag) too often can shorten the performance life of the drive's internal memory.
 2. Although RYE and RYF are triggered by the rising edge of the signal, they are otherwise enabled depending on the value that is input. When switching between monitors using RYC (Monitor Reference), RYC needs to be turned off and then back on again after the monitor code has been changed.

■ Drive → PLC

Table 8 Remote I/O Table (Drive → PLC)

Device	Signal Name	Description	Default
RX0	Forward Run	ON: Forward Run Command Present (includes DC Injection Braking) OFF: No Forward Run Command	-
RX1	Reverse Run	ON: Reverse Run Command Present OFF: No Reverse Run Command (includes DC Injection Braking)	-
RX2	Terminals MA, MB, MC Function	Multi-function output: H2-01	(H2-01 = E: Fault)

8 CC-Link Data Table

Device	Signal Name	Description	Default
RX3	Speed Agree	ON: Output frequency is between frequency reference and the detection width set to L4-02.	–
RX4	During Stall Prevention	–	–
RX5	During Undervoltage	–	–
RX6	Terminal P1 Function	Multi-function output: H2-02	(H2-02 = 0: During Run)
RX7	Terminal P2 Function	Multi-function output: H2-03	(H2-03 = 2: Speed Agree 1)
RX8, 9	Reserved	–	–
RXA	CC-Link Option Fault	Comm. error between drive and CC-Link device	–
RXB	Monitoring Motor Revolutions	ON: Currently monitoring motor revolutions.	Data is stored in remote register RW _{R1} .
RXC	Obtain Monitor Data	ON: Monitor data has been updated.	–
RXD	Frequency Setting Ready 1	ON: Displays the main frequency reference that has been set.	–
RXE	Frequency Setting Ready 2	ON: Displays the data set to d1-01 (Frequency Reference 1). Note: Also sets the main frequency reference at the same time.	–
RXF	Command Code Execute Complete	ON: Displayed after the specified command code has been executed. RXF signal switches off when the RYF command is no longer present.	–
RX10 to 19	Reserved	–	–
RX1A	Error	ON: Fault occurred on the drive side.	–
RX1B	Remote Station Ready	ON: Drive is ready to operate.	–
RX1C to 1F	Reserved	–	–

Note: If making frequent setting changes, use RYD (Frequency Reference 1 flag) for setting the register. Using RYE (Frequency Reference 2 flag) too often can shorten the performance life of the drive's internal memory.

◆ Remote Register

■ PLC → Drive

Table 9 Remote Register (PLC → Drive)

Remote Register	Name	Description	Request Flag
RW _{W0}	Monitor Code	Sets the code number of the items to be displayed by the monitor.	RYC (Monitor Execute Request)
RW _{W1}	Frequency Setting	Indicates which value is to be used to set the frequency.	<ul style="list-style-type: none"> • RYD (Frequency Reference 1) • RYE (Frequency Reference 2)
RW _{W2}	Command Code	Sets the command code to execute functions such as the fault reset, fault history, parameter read, and so on.	RYF (Command Code Execute Request)
RW _{W3}	Write Data	Sets the value to be used along with RW _{W2} (Command Code) as needed.	

■ Drive → PLC

Table 10 Remote Register (Drive → PLC)

Remote Register	Name	Description	Check Flag
RW _{R0}	Monitor Data	Monitor data is stored according to RW _{W0} (Monitor Code).	RXC (while monitoring)
RW _{R1}	Output Frequency	Output frequency has been set without any errors. Set in the units specified by 01-03 (Frequency Reference Setting Units).	–
RW _{R2}	Response Code	<ul style="list-style-type: none"> • Sets 00H when there are no problems with RW_{W2} (Command Code) and RW_{W3} (Write Data). • Sets 01H through 03H if an error occurs. • Response Code: 00h: Normal 01h: Write-mode error (attempted to write during run, etc.) 02h: Command code error 03h: Data setting range error 	RXF (Command Code Execute Complete)
RW _{R3}	Read Data	Data is set according to the command code.	

9 Troubleshooting

◆ Drive-Side Error Codes

Drive-side error codes appear on the drive's LED operator. Causes of the errors and corrective actions are listed in [Table 11](#).

For additional error codes that may appear on the LED operator screen, refer to the V1000 Technical Manual.

■ Faults

Both bUS (CC-Link Option Communication Error) and EF0 (External Fault Input from the CC-Link Option) can appear as an alarm or as a fault. When a fault occurs, the digital operator ALM LED remains. When an alarm occurs, the digital operator ALM LED flashes.

If communication stops while the drive is running, answer the following questions to help remedy the fault:

- Is the CC-Link Option properly installed?
- Is the communication line properly connected to the CC-Link Option? Is it loose?
- Is the PLC program working? Has the PLC CPU stopped?
- Did a momentary power loss interrupt communications?

Table 11 Fault Display and Possible Solutions

LED Operator Display		Fault Name
<i>bUS</i>	bUS	CC-Link Option Communication Error
		After establishing initial communication, the connection was lost. Only detected when the run command or frequency reference is assigned to the option (b1-01 = 3 or b1-02 = 3).
Cause		Possible Solution
Master controller (PLC) has stopped communicating.		Check for any faulty wiring. ⇒ Correct any wiring problems.
Communication cable is not connected properly.		⇒ Take care of any grounding problems or disconnects wires.
A data error occurred due to noise		Check the various options available to minimize the effects of noise. ⇒ Take steps to counteract noise in the control circuit wiring, main circuit lines, and ground wiring. ⇒ If the magnetic contactor is identified as a source of noise, install a surge absorber to the contactor coil. ⇒ Use cables recommended by Yaskawa, or another type of shielded line. The shield should be grounded on the PLC side and on the option unit side.
CC-Link Option is damaged.		⇒ If there are no problems with the wiring and the error continues to occur, replace the CC-Link Option.

LED Operator Display		Fault Name
EFO	EF0	External Fault Input from CC-Link Option The alarm function for an external device has been triggered.
Cause		Possible Solution
An external fault is being sent from the master controller (PLC).		⇒ Remove the cause of the external fault. ⇒ Reset the external fault input from the PLC device.
Problem with the PLC program		⇒ Check the program used by the PLC and make the appropriate corrections.


LED Operator Display		Fault Name
oFA00	oFA00	CC-Link Option Fault (port A) CC-Link Option is not properly connected.
Cause		Possible Solution
Non-compatible option connected to the drive		⇒ Connect an option that is compatible with the drive.

LED Operator Display		Fault Name
oFA01	oFA01	CC-Link Option Fault (port A) CC-Link Option is not properly connected.
Cause		Possible Solution
Problem with the connectors between the drive and CC-Link Option		⇒ Turn the power off and check the connectors between the drive and CC-Link Option.


LED Operator Display		Fault Name
oFA03	oFA03	CC-Link Option Fault (port A) CC-Link Option self-diagnostics error
Cause		Possible Solution
CC-Link Option hardware fault		⇒ Replace the CC-Link Option. Contact Yaskawa for consultation.


LED Operator Display		Fault Name
oFA04	oFA04	CC-Link Option Fault (port A) CC-Link Option Flash write mode
Cause		Possible Solution
CC-Link Option hardware fault		⇒ Replace the CC-Link Option. Contact Yaskawa for assistance.

9 Troubleshooting

LED Operator Display		Fault Name
 oFA30 to oFA43	oFA30 to oFA43	CC-Link Option Fault (port A)
		Communication ID error
Cause		Possible Solution
CC-Link Option hardware fault		⇒ Replace the CC-Link Option. Contact Yaskawa for assistance.

■ Minor Faults and Alarms

LED Operator Display		Minor Fault Name	
 AEr	AEr	Station Address Error	
		CC-Link Option is set to an address outside the allowable setting range.	
Cause		Possible Solution	Minor Fault (H2-□□ = 10)
Address outside the specified address range		⇒ Set F6-10 to an address within the specified range.	YES

LED Operator Display		Minor Fault Name	
 CALL	CALL	Serial Communication Transmission Error	
		Communication has not yet been established.	
Cause		Possible Solution	Minor Fault (H2-□□ = 10)
Communication wiring is faulty, there is a short circuit, or something is not connected properly.		Check for wiring errors. ⇒ Correct the wiring. ⇒ Remove and ground shorts and reconnect loose wires.	YES
Programming error on the master side		⇒ Check communications at start-up and correct programming errors.	
Communication circuitry is damaged.		Perform a self-diagnostics check. ⇒ Replace the drive if the fault continues to occur.	

◆ Fault LED Display on CC-Link Option Side

■ Checking LED Operation

Table 12 LED Display

L.RUN	Switches on when data is being received normally. Turns off when the receive data is interrupted.
SD	Lights whenever the drive is sending data.
RD	Lights whenever the drive is receiving data.
L.ERR	Lights when a CRC or abort error occurs.

Note: If communication stops while the drive is running, check the following:

- Is thC-Link properly installed?
- Is the CC-Link communication line connected to the CC-Link Option correctly? Is it loose?
- Is the PLC program working? Has the PLC CPU stopped?
- Did a momentary loss in power interrupt communications?

■ Faults that Occur with a Single Drive

The example below demonstrates how to read the LED display on the CC-Link Option to determine the cause of a fault and corrective action.

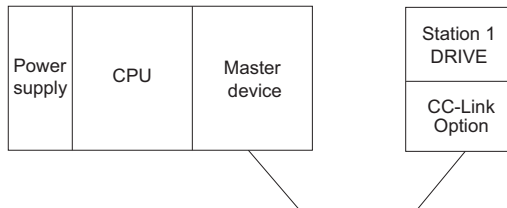


Figure 16 Connecting a Single Drive

9 Troubleshooting

Table 13 LED Fault Display for CC-Link Option with a Single Drive

○: On / □: Flashing / ×: Off / *: Either on or off

L.RUN	SD	RD	L.ERR	Cause	Possible Solution
○	○	○	×	Normal communications	—
○	○	○	□	Error has occurred but communication is normal	⇒Remove the source of noise interference.
○	○	×	□	Problem with the hardware	⇒Try cycling the power. Replace the CC-Link Option if the problem continues.
○	○	×	×	Problem with the hardware	⇒Try cycling the power. Replace the CC-Link Option if the problem continues.
○	×	○	□	CRC error with the data received, and no response can be sent	⇒Remove the source of noise interference.
○	×	○	×	No station address received	⇒Check the PLC program and the operation where the problem occurred.
○	×	×	□	Problem with the hardware	⇒Try cycling the power. Replace the CC-Link Option if the problem continues.
○	×	×	×	Problem with the hardware	⇒Try cycling the power. Replace the CC-Link Option if the problem continues.
×	○	○	□	A response was received after polling, but a CRC error occurred when the reflex data was checked	⇒Remove the source of noise interference.
×	○	○	×	Problem with the hardware	⇒Try cycling the power. Replace the CC-Link Option if the problem continues. ⇒See if the master device is actually set to function as a remote device station.
×	○	×	□	Problem with the hardware	⇒Try cycling the power. Replace the CC-Link Option if the problem continues.
×	○	×	×	Problem with the hardware	⇒Try cycling the power. Replace the CC-Link Option if the problem continues.
×	×	○	□	CRC errors occurs when the station address is checked.	⇒Remove the source of noise interference.
×	×	○	×	<ul style="list-style-type: none"> • No station address • Cannot receive station address due to noise interference 	⇒Remove the source of noise interference.

○: On / □: Flashing / ×: Off / *: Either on or off

L.RUN	SD	RD	L.ERR	Cause	Possible Solution
×	×	×	□	Problem with the hardware	⇒Try cycling the power. Replace the CC-Link Option if the problem continues.
×	×	×	×	Data cannot be received (CC-Link communications cable may be disconnected)	⇒Check the wiring.
×	×	*	○	The station address or communications speed is set incorrectly	⇒Enter the proper settings and cycle power.
○	○	○	□	The station address or communications speed was changed without cycling power afterwards.	⇒Return any incorrect settings to their original values and cycle power.⇒Enter the proper settings and cycle power.

Note: SD and RD may appear to flash with slower baud rates.

■ Faults when running multiple drives

The example below demonstrates how to read the LED display on the CC-Link Option to determine the cause of a fault and the corrective action to take when multiple drives are running from the same network. The example assumes that SW, M/S, and PRM on the master device are all off, indicated that the master device is operating normally.

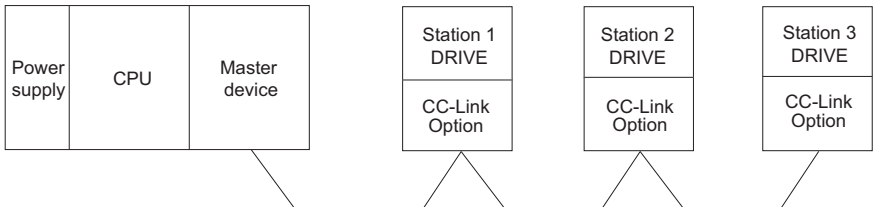


Figure 17 Connecting Multiple Drives on the Same Network

9 Troubleshooting

Table 14 LED Fault Display for CC-Link Option with Multiple Drives

○: On / □: Flashing / ×: Off / *: Either on or off

Master		LED Status			Cause	Corrective Action
		Remote Device Addresses (CC-Link Option)				
		Station 1	Station 2	Station 3		
TIME LINE ○ or TIME LINE × LINE ○		L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	Normal operation	—
		L.RUN × SD × RD × L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	The CC-Link Option for the first station is not properly installed.	⇒Make sure the CC-Link Option and drive are connected together properly.
		L.RUN * SD * RD * L.ERR *	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	The CC-Link Option for the first station is damaged (most often all LEDs are out). Note: Sometimes and error will appear on the drive's LED operator	⇒Replace the CC-Link Option.
		L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN × SD * RD * L.ERR ×	L.RUN × SD * RD * L.ERR ×	Because L.RUN after Station 2 is off, either the comm. line between Station 1 and Station 2 is disconnected, or the terminal block has come loose.	Make sure components are connected correctly, using the LEDs as a guide to indicate a proper connection.
		L.RUN × SD * RD * L.ERR ×	L.RUN × SD * RD * L.ERR ×	L.RUN × SD * RD * L.ERR ×	Comm cable has short-circuited	⇒Look for any short-circuits along the communication lines and fix any problems.
		L.RUN × SD * RD * L.ERR *	L.RUN × SD * RD * L.ERR *	L.RUN × SD * RD * L.ERR *	Comm cable is not wire properly	⇒Check the wiring for the CC-Link Option terminal block and fix and mistakes.
		L.RUN × SD * RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN × SD * RD ○ L.ERR ×	The CC-Link Options for Station 1 and Station 3 have been assigned the same address.	⇒Enter the correct station address and cycle power.
		L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN × SD × RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	The CC-Link Option for Station 2 has a different comm speed setting than the master device.	⇒Set the correct communication speed and cycle power.

9 Troubleshooting

○: On / □: Flashing / ×: Off / *: Either on or off

Master		LED Status			Cause	Corrective Action
		Remote Device Addresses (CC-Link Option)				
		Station 1	Station 2	Station 3		
TIME LINE or TIME LINE	○ ○	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR □	The settings for the CC-Link Option connected to Station 3 were changed without cycling power.	⇒Return any incorrect settings to their original values and cycle power. ⇒Enter the proper settings and cycle power.
	× ○	L.RUN × SD × RD ○ L.ERR ○	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×		
TIME LINE or TIME LINE	× × ○ ×	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ○	L.RUN ○ SD ○ RD ○ L.ERR ×	The CC-Link Option connected to Station 2 is experiencing noise interference (L.RUN is sometimes off).	⇒Make sure that the CC-Link Options, drives, and master device are all grounded properly.
		L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ○	L.RUN ○ SD ○ RD ○ L.ERR ○	Noise interference along the cable running between Station 2 and Station 3. (L.RUN is sometimes off)	⇒Reconnect the comm line to the SLD terminal on the CC-Link Option. Also make sure that all power cables are properly separated from comm lines (at least 100 mm away).
		L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ×	L.RUN ○ SD ○ RD ○ L.ERR ○	Terminal resistor not connected. (L.RUN is sometimes off)	⇒Set up the final station in the series for terminal resistor.

10 Specifications

◆ Specifications


Table 15 Option Specifications

Model	SI-C3/V (PCB model: SI-C3)
Station Type	Remote device station
No. of Occupied Stations	1
Comm. Speed	156 kbps to 10 Mbps
Ambient Temperature	-10°C to +50°C
Humidity	up to 95% RH (no condensation)
Storage Temperature	-20°C to +60°C (allowed for short-term transport of the product)
Area of Use	Indoors (free of corrosive gas, airborne particles, etc.)
Altitude	Up to 1000 m

◆ Revision History

The revision dates and numbers of the revised manuals are given on the bottom of the back cover.






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